

Kurdyka-Łojasiewicz inequality and subgradient trajectories : the convex case

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Łojasiewicz inequality [Łojasiewicz 1963]

$f : \mathbb{R}^N \rightarrow \mathbb{R}$ is **analytic**.

Let a be a critical point of f .

Then there exists a neighborhood U of a , $C > 0$ and $\theta \in (0, 1)$ such that

$$\|\nabla f(x)\| \geq |f(x) - f(a)|^\theta \quad \text{for all } x \in U.$$

⇒ Finite length of the gradient trajectories, Every critical point is limit of a gradient trajectory, etc.

To simplify :

H is a real Hilbert space

$f : H \rightarrow [0, +\infty)$ is smooth ($f \geq 0$)

For all $r > 0$, $C_r := \{f \leq r\}$

(A0) (0 is a critical point and a global minimum)

$0 \in C_0$

(A1) (0 is an isolated critical value)

There exists $r_0 > 0$ such that :

$x \in C_{r_0}$ and $f(x) > 0 \Rightarrow \nabla f(x) \neq 0$

(A2) (Sublevel compactness)

There exists $r_0 > 0$ such that : $C_{r_0} = \{f \leq r_0\}$ is compact.

We say that f satisfies Kurdyka-Łojasiewicz inequality [Kurdyka 1998] if :

There exists $\varphi \in KL(0, r_0)$ such that :

$$\|\nabla(\varphi \circ f)(x)\| \geq 1 \quad \text{for all } x \in C_{r_0} \setminus C_0.$$

where :

$$KL(0, r_0) = \left\{ \varphi : [0, r_0] \rightarrow \mathbb{R}_+ \text{ continuous,} \right. \\ \left. \varphi(0) = 0, \varphi \in C^1(0, r_0), \varphi' > 0 \right\}.$$

► Lojasiewicz inequality is a particular case with

$$\varphi(r) = \frac{1}{c(1-\theta)} r^{1-\theta}.$$

From now on, we assume that

f is **convex**

Issues :

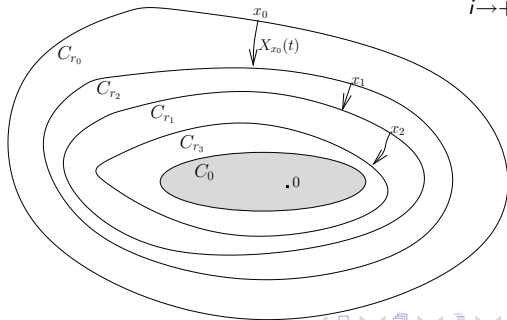
- 1 Characterizations of the KŁ-inequality in the convex case
- 2 Does a convex function satisfy the KŁ-inequality?

Gradient dynamical system :

$$\begin{cases} \dot{X}_x(t) = -\nabla f(X_x(t)), & t \geq 0 \\ X_x(0) = x \end{cases}$$

A **piecewise gradient curve** γ is a countable family of gradient curves $X_{x_i}([0, t_i))$ with

$$f(X_{x_i}(0)) = f(x_i) = r_i, \quad f(X_{x_i}(t_i)) = r_{i+1} \quad r_i \downarrow 0 \quad i \rightarrow +\infty$$



Lemma. For all $x_0 \in C_{r_0} \setminus C_0$,

- 1 $t \mapsto f(X_{x_0}(t))$ is convex, $L^1(0, +\infty)$ and decreasing with limit 0.
- 2 Each trajectory goes closer to all minima at the same time, i.e., for each $a \in C_0$,

$$\frac{d}{dt} \|X_{x_0}(t) - a\|^2 \leq -2f(X_{x_0}(t)) < 0.$$

- 3 For all $T > 0$,

$$\int_0^T \|\dot{X}_{x_0}(t)\| dt \leq \frac{1}{\sqrt{2}} \|x_0\| \sqrt{\log T}.$$

Theorem. The following statements are equivalent :

- 1 f satisfies the KŁ-inequality in C_{r_0} :
 $\|\nabla(\varphi \circ f)(x)\| \geq 1$ with $\varphi \in KL(0, r_0)$.
- 2 f satisfies the KŁ-inequality **globally** in H with $\varphi \in KL(0, +\infty)$ which is **concave**.
- 3 $r \in (0, r_0] \mapsto \frac{1}{\inf_{f(x)=r} \|\nabla f(x)\|}$ is integrable.
- 4 For all piecewise gradient curves γ in C_{r_0} we have

$$\text{length}(\gamma) = \sum_{i=0}^{\infty} \int_0^{t_i} \|\dot{X}_{x_i}(t)\| dt < \infty.$$

Length of the 'convex' gradient curves

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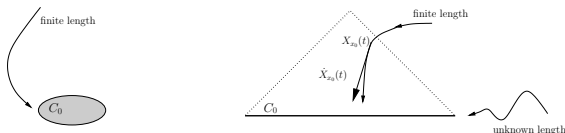
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[Brézis 1973] Given $x_0 \in C_{r_0}$, do we have

$$\text{length}(X_{x_0}) = \int_0^\infty \|\dot{X}_{x_0}(t)\| dt < \infty ?$$

Theorem. [Brézis 1973] Yes if $\text{int}(\text{argmin}(f)) \neq \emptyset$.



Theorem. [Baillon 1978] No in general (counter-example in infinite dimension)

A sufficient condition for a convex function to satisfy KŁ-inequality

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Theorem. Assume that there exists $m : [0, +\infty) \rightarrow [0, +\infty)$ continuous increasing with $m(0) = 0$ such that $f \geq m(\text{dist}(\cdot, C_0))$ on C_{r_0} and

$$\int_0^{r_0} \frac{m^{-1}(r)}{r} dr < +\infty \quad (\text{growth condition}). \quad (1)$$

Then KŁ-inequality holds for f .

- ▶ Proof : $f(x) \leq \langle \nabla f(x), x - p_{C_0}(x) \rangle$
 $\leq \|\nabla f(x)\| \text{dist}(x, C_0) \leq \|\nabla f(x)\| m^{-1}(f(x)).$
- ▶ non analytic examples : $m(r) = \exp(-1/r^\alpha)$, $\alpha \in (0, 1)$ satisfies (1).

Theorem. There exists a C^2 convex function $f : \mathbb{R}^2 \rightarrow \mathbb{R}_+$ with $\{f = 0\} = D(0, 1)$ for which KŁ-inequality fails.

► Note that the gradient trajectories have uniform finite length.

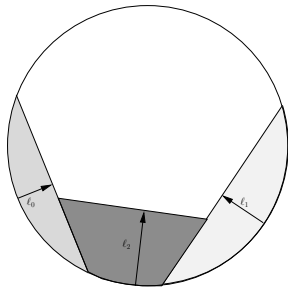
An auxiliary problem

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A farmer rakes its (convex) field in several steps in the following way :



If he is unlucky, is it possible that he walks an infinite path ?

(i.e. $\sum_{i \geq 0} l_i = +\infty$)

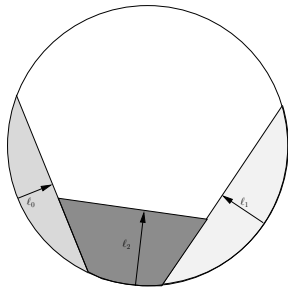
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Answer : **Yes!**

Lemma. There exists a decreasing sequence of compact convex subsets $\{T_k\}_k$ in \mathbb{R}^2 such that :

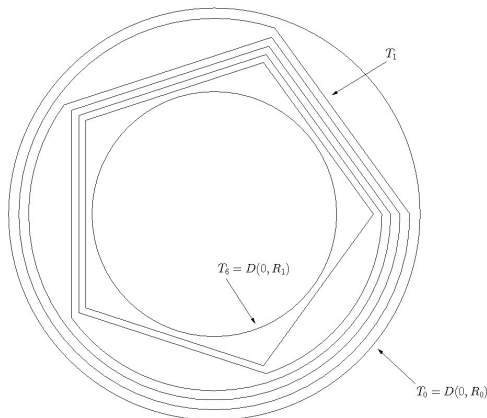
- (i) T_0 is the disk $D := D(0, 2)$;
- (ii) $T_{k+1} \subset \text{int } T_k$ for every $k \in \mathbb{N}$;
- (iii) $\bigcap_{k \in \mathbb{N}} T_k$ is the unit disk $D(0, 1)$;
- (iv) $\sum_{k=0}^{+\infty} \text{dist}_{\text{Hausdorff}}(T_k, T_{k+1}) = +\infty$.

Picture of the sequence of convex sets

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$$\ell_k := \text{dist}_{\text{Hausdorff}}(T_k, T_{k+1}) \approx R_i - R_{i+1} \text{ and } N_i \approx \frac{1}{\sqrt{R_i - R_{i+1}}}$$

It suffices to take $R_i - R_{i+1} = \frac{1}{i^2}$ in order that

$$\sum_i R_i - R_{i+1} < \infty \text{ and}$$

$$\sum_k \ell_k \approx \sum_i N_i (R_i - R_{i+1}) \approx \sum_i \sqrt{R_i - R_{i+1}} = +\infty.$$

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- ▶ Construction of a convex function with prescribed sublevel sets T_k : [Torralba 1996].
- ▶ Smoothing of the function.